## Machine learning in Exoplanets

Ariel Summer School, Biarritz

September 2023 Institute
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erc


Science \& Technology
Facilities Council

## Progress on Al has accelerated significantly <br> Mainly due to an exponential increase in compute

${\underset{n}{n}=121}_{\text {Training compute (FLOPs) of milestone Machine Learning systems over time }}^{\text {nen }}$
$n=$


Figure 1: Trends in $n=121$ milestone ML models between 1952 and 2022. We distinguish three eras. Notice the change of slope circa 2010, matching the advent of Deep Learning; and the emergence of a new large-scale trend in late 2015. Savilla et al. 2022, arXiv: 2022:05924v2

# GPTs are GPTs: An Early Look at the Labor Market Impact <br> Potential of Large Language Models 

Tyna Eloundou ${ }^{1}$, Sam Manning ${ }^{1,2}$, Pamela Mishkin*1, and Daniel Rock ${ }^{3}$<br>March 27, 2023 arXiv: 2303.10130v4

| Group | Occupations with highest exposure | \% Exposure | Metric: <br> At least 50\% of tasks will be automated/augmented |
| :---: | :---: | :---: | :---: |
| Human $\alpha$ | Interpreters and Translators | 76.5 |  |
| GPT technology alone | Survey Researchers | 75.0 |  |
|  | Poets, Lyricists and Creative Writers | 68.8 |  |
|  | Animal Scientists | 66.7 |  |
|  | Public Relations Specialists | 66.7 | $\alpha=$ GPT only |
| Human $\beta$ | Survey Researchers | 84.4 |  |
| GPT technology + some software augmentation | Writers and Authors | 82.5 | $\beta=\mathrm{GPT}+50 \%$ <br> specialised software on top of GPT |
|  | Interpreters and Translators | 82.4 |  |
|  | Public Relations Specialists | 80.6 |  |
|  | Animal Scientists | 77.8 |  |
| Human $\zeta$ | Mathematicians | 100.0 | $\zeta=\mathrm{GPT}+$ specialised |
| GPT technology + full software augmentation | Tax Preparers | 100.0 | software on top of GPT |
|  | Financial Quantitative Analysts | 100.0 |  |
|  | Writers and Authors | 100.0 |  |
|  | Web and Digital Interface Designers Humans labeled 15 occupations as | d." 100.0 |  |

# A significant number of tasks will be affected 

## Much of our work flow will change in the next years



Table 6: Mean exposure to GPTs by job zone. For each job zone, we also present the median of median annual income for each constituting occupation in USD, and the total number of workers in all occupations for that job zone, in the thousands.

## State of ML in Exoplanets




A lot of Al papers...
ML+AI arXiv papers per month


There's a lot of AI around ... We can't cover it all in 1.5 hours

## What the Exoplanet Science addressable with AI?

- Realistic instrument noise simulations/ detrending
- Better data de-trending (instrumental noise and/or stellar)
- Faster and better inverse modelling (retrievals and light curve fitting)
- Faster generative models (e.g. chemistry, radiative transfer, circulation, condensation, etc)
- Many other things...



## Let's focus on some Al applications to Exoplanet Atmospheric retrievals

-What if we can train an Al to quickly and reliably classify and measure planet atmospheres?


## A quick word on using Al

## DON'T!

## Only proceed if you really have to ...

## But if you have to use AI/ML A quick cheat sheet:

- PCA, clustering and component separation, Random Forests...

Use sklearn (https://scikit-learn.org/stable/index.html)

- Deep learning

Use PyTorch (https://pytorch.org/)

- Probabilistic programming

Use PyRo (https://pyro.ai)

- Simulation based inference

Use SBI (https://www.mackelab.org/sbi/)

- Great resources for models and tutorials

HuggingFace (https://huggingface.co/)
Papers With Code (https://paperswithcode.com/

## Agenda

## Unsupervised learning

- Clustering (Nearest Neighbours, K-means)
- Component Separation (PCA, ICA)


## (Self-)Supervised learning

- Random Forests
- Multi-layer perceptrons
- Autoencoders
- Bayesian Neural Networks
- Variational Inference
- Explainability



## Let's reproduce some recent papers today

Supervised Machine Learning for Analysing Spectra of
Exoplanetary Atmospheres

Dohln Mónnunar Mailo 1,2 Chlon Fichor ${ }^{2}$

## Reducing the complexity of chemical networks via interpretable autoencoders

Retrieving exoplanet atmospheric parameters using
T. Grassi ${ }^{1,2, \star}$, F. Nauman ${ }^{3}$, J. P. Ramsey ${ }^{4}$, S. Bovino ${ }^{5}$, G. Picogna ${ }^{1,2}$, and B. Ercolano ${ }^{1,2}$ random forest regression
rte München, Scheinerstr. 1, D-81679 München, Germany
rigin and Structure of the Universe, Boltzmannstr.2, D-85748 Garching bei München, Germany

Disentangled Representation Learning for Astronomical Chemical Tagging
Patcharawee Munsaket ${ }^{1 *}$, Supachai Awiphan ${ }^{2}$, Poemw and Eamonn Kerins ${ }^{4}$
${ }^{1}$ School of Physics, Institute of Science, Suranaree Univ Ratchasima 30000, Thailand

Unsupervised Machine Learning for Exploratory Data Analysis of Exoplanet Transmission Spectra

## Accurate Machine-learning Atmospheric Retrieval via a Neural-network Surrogate

 Model for Radiative TransferMolecular generative model based on conditional variational autoencoder for c novo molecular design

Michael D. Himes ${ }^{1} \oplus$, Joseph Harrington ${ }^{2} \oplus$, Adam D. $^{\circ}$ Cobb $^{3} \oplus$, Atılım Günes Baydin ${ }^{3} \oplus$, Frank Soboczenski ${ }^{4} \oplus$, Molly D. O'Beirne ${ }^{5} \oplus$, Simone Zorzan ${ }^{6} \oplus$, David C. Wright ${ }^{1} \oplus$, Zacchaeus Scheffer ${ }^{1} \oplus$, Shawn D. Domagal-Goldman ${ }^{7}{ }^{\bullet}\left({ }^{\top}\right.$, and Giada N. Arney ${ }^{7}$ (1)
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Jaechang Lim ${ }^{1}$, Seongok Ryu ${ }^{1}$, Jin Woo Kim ${ }^{1}$ and Woo Youn Kim ${ }^{1,2^{*} \odot}$

## A quick word on Explainability



## Introducing a generic data set

For most examples, our data set is an array of spectra


Your data set should cover a wide range of parameters



## Principal Component Analysis (PCA)



Single Value Decomposition
matrix of eigenvectors


Projection to orthogonal axes

$$
\begin{aligned}
\mathbf{X} & =\mathbf{U} \Sigma \mathbf{V}^{T} \\
\mathbf{U}^{T} \mathbf{X} & =\Sigma \mathbf{V}^{T} \\
\mathbf{U}^{T} \mathbf{X} & =\mathbf{Z} \& \text { z-score }
\end{aligned}
$$

The Planetary Science Journal, 3:205 (12pp), 2022 September

## Unsupervised Machine Learning for Exploratory Data Analysis of Exoplanet Transmission Spectra

 Physics Department, University of Florida, Gainesville, FL 32653, USA; matcheva@ufl.edu Received 2022 April 7; revised 2022 July 1; accepted 2022 August 1; published 2022 September 1



Figure 4. Scatter plots of 25,000 data points: the average $\mu(M)$ (plotted on the $x$-axis) vs. the standard deviation $\sigma(M)$ (plotted on the $y$-axis). In each panel, the points are color-coded by the value of one of the five target variables, indicated at the top. The black $\star$ symbol marks the location of the hot gas giant exoplanet WASP-12b.

## Sklearn example of PCA

```
#importing PCA routine
from sklearn.decomposition import PCA
```

```
N = 1000 #data index to take the first 1000 spectra only
```

N = 1000 \#data index to take the first 1000 spectra only
\#running PCA
\#running PCA
pca = PCA(n_components=3)
pca = PCA(n_components=3)
pca.fit(train_data[:N,0:13]) \#performing the PCA transform
pca.fit(train_data[:N,0:13]) \#performing the PCA transform
PCA_out = pca.fit_transform(train_data[:N,0:13]) \#transforming your data into PCA space

```
PCA_out = pca.fit_transform(train_data[:N,0:13]) #transforming your data into PCA space
```

Google Colab notebook:
https://bit.ly/ExoAI_PCA

## Spectral clustering of exoplanets

-Turns out that most of your information in your spectral data can be described by only 2 - 3 principal components


Figure 7. The same as Figure 4, but plotted in the plane of the first and second PCA components (top row) or the plane of the second and third PCA component (bottom row).

## Spectral clustering of exoplanets



Figure 7. The same as Figure 4, but plotted in the plane of the first and second PCA components (top row) or the plane of the second and third PCA components (bottom row).

## Clustering (k-means)

-The PCA components show distinct features... can we cluster them? - Yes

- Many clustering algorithms exist. All the good ones are on sklearn and you can try them all easily


## K-means

- Given a number of given clusters, it calculates the position of the cluster mean (i.e. centre) that minimises both the distance of the surrounding points and the variance around the mean

Google Colab notebook:
https://bit.ly/ExoAI_PCA



## Decision tree regression

-Decision tress are a supervised machine learning technique
-They find a mapping between data ( X ) and labels/results ( Y )



## Random Forest regression



- Individual Trees are not very good predictors (they are called 'weak predictors')
-By averaging many weak predictors you get a strong predictor
- Averaging/summing many trees is called 'ensembling'


## Using Random Forrests to classify a hot Jupiter

- Radom Forests are an ensemble of multiple decision trees
- One of the oldest and most stable machine learning methods
- Individual Forrests are by nature interpretable (ensembles not)
- Easy and fast to train
- Do not generalise as well as deep learning and struggle to cope with large data sets



Marquez-Neila et al. 2018 see also e.g. Nixon \& Madhusudan 2019

## Feature importance in Random Forrests

- Perturbation based analysis gives understanding of what data has greatest impact


Marquez-Neila et al. 2018
see also e.g. Nixon \& Madhusudan 2019

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Marquez-Neila et al. 2018
see also e.g. Nixon \& Madhusudan 2019

## Using Random Forrests

By reading out the individual outputs, you can generate Parameter distributions Note these are NOT formal Bayesian posterior distributions



Marquez-Neila et al. 2018
see also e.g. Nixon \& Madhusudan 2019

## Using Random Forrests

## Pro:

-Easy to implement and fast to run

- Is in principle fully interpretable, also known as a 'white box model'
- Can easily derive Feature Importance diagnostics
-Can provide a probability over parameters, can be extended into Bayesian framework


## Con:

- Does not scale well with data size
- May not be expressive enough with a realistic number of trees
- Interpretability becomes difficult for many and deep trees


## Using Random Forrests

```
>>> from sklearn.ensemble import RandomForestRegressor
>>> from sklearn.datasets import make_regression
>>> X, y = make_regression(n_features=4, n_informative=2,
    random state=0, shuffle=False)
>>> regr = RandomForestRegressor(max_depth=2, random_state=0)
>>> regr.fit(X, y)
RandomimorestRegressor(.:.)
>>> print(regr.predict([[0, 0, 0, 0]]))
[-8.32987858]
```


## Google Colab notebook:

 https://bit.ly/ExoAI_RF
/imagine prompt: theatre curtains for an interlude

## Machine Learning and Deep Learning


https://blogs.nvidia.com/blog/2016/07/29/whats-difference-artificial-intelligence-machine-learning-deep-learning-ai/

## Hebbian learning and the perceptron

66
Let us assume that the persistence or repetition of a reverberatory activity tends to induce lasting cellular changes that add to its stability. ... When an axon of cell $A$ is near enough to excite a cell $B$ and repeatedly or persistently takes part in firing it, some growth process or metabolic change takes place in one or both cells such that A's efficiency, as one of the cells firing B, is increased

Donald Hebb (The Organisation of Behaviour, 1949)


Hebbian learning and the perceptron


## Hebbian learning and the perceptron

## Perceptron

Rosenblatt (1958)


$$
y=f(x)= \begin{cases}1 & \text { if } \sum_{i} w_{i} x_{i}+b>0 \\ 0 & \text { otherwise }\end{cases}
$$

Hebbian learning and the perceptron

## Perceptron

Rosenblatt (1958)


Many flavours of activation functions

## Sigmoid

$\sigma(x)=\frac{1}{1+e^{-x}}$

tanh
$\tanh (x)$


## ReLU

$\max (0, x)$

Leaky ReLU $\max (0.1 x, x)$


## Maxout

$\max \left(w_{1}^{T} x+b_{1}, w_{2}^{T} x+b_{2}\right)$

## ELU

$$
\begin{cases}x & x \geq 0 \\ \alpha\left(e^{x}-1\right) & x<0\end{cases}
$$



Yes... there is also an activation function dance...


## Machine Learning and Deep Learning


https://blogs.nvidia.com/blog/2016/07/29/whats-difference-artificial-
intelligence-machine-learning-deep-learning-ai/

## Multi-layer Perceptron

- First introduced by Rosenblatt in 1958 along with the Perceptron
- Usually trained by backpropagation (first introduced in 1970 as the inverse of automatic differentiation. Came back into fashion in the 2010s when GPUs became readily available.
- Calculate the derivative of the cost function $C(y, g(x))$ using chain rule

Single layer


$$
y=f\left(\sum_{i} w_{i} x_{i}+b\right)
$$

Multi-Layer Perceptron (MLP)


## Machine Learning and Deep Learning


https://blogs.nvidia.com/blog/2016/07/29/whats-difference-artificial-
intelligence-machine-learning-deep-learning-ai/

## The 2 Al winters



# Feed forward nets \& Autoencoders 

## Let's simplify our pictograms



Multi-layer perceptron (MLP) Feed forward network

## Accurate Machine-learning Atmospheric Retrieval via a Neural-network Surrogate Model for Radiative Transfer

Michael D. Himes ${ }^{1} \oplus$, Joseph Harrington ${ }^{2} \oplus$, Adam D. Cobb $^{3} \oplus$, Atılım Günes Baydin ${ }^{3} \oplus$, Frank Soboczenski ${ }^{4} \oplus$, Molly D. O'Beirne ${ }^{5} \oplus$, Simone Zorzan ${ }^{6} \oplus$, David C. Wright ${ }^{1}{ }^{(©)}$, Zacchaeus Scheffer $\left.{ }^{1}{ }^{( }\right)$, Shawn D. Domagal-Goldman ${ }^{7} \oplus{ }^{\bullet}$, and Giada N. Arney ${ }^{7}$ ©
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NASA Goddard Space Flight Center, Greenbelt, MD, USA
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## Neural Network surrogate models

Replacing the slow astrophysical model with a faster Neural Network surrogate
Maintaining traditional Bayesian sampling to calculate parameter distributions


Himes et al. 2021

## Doing a good job at approximating the radiative transfer model






## Reproducing their model in PyTorch

## Radiative transfer parameters

(Mol abundances, Rp, Tp, etc)


Final spectrum

```
import torch
import torch.nn as nn
#setting up model
model = nn.Sequential(
    nn.Linear(12,256)
    nn.Conv1D(256, 4096,1,stride=1),
    nn.LeakyReLU(),
    nn.Linear(4096, 4096),
    nn.LeakyReLU(),
    nn.Linear(4096, 4096),
    nn.LeakyReLU(),
    nn.Conv1D(n,1,stride=1),
)
#definining loss function
loss_fn = nn.MSELoss()
loss = loss_fn(spectra, forward_model_parameters)
#defining optimizer
optimizer = torch.optim.Adam(model.parameters(), lr=0.001)
#training the model over num_epochs cycles
for n in range(num_epochs):
    y_pred = model(X)
    loss = loss_fn(y_pred, y)
    optimizer.zero_grad()
    loss.backward()
    optimizer.step()
```


## Autoencoders



Multi-layer perceptron (MLP) Feed forward network

Read chapter 14 in: https://www.deeplearningbook.org/

## Autoencoders



- Output must equal input
- Self-supervised learning
- Non-linear data compression and clustering
- Not probabilistic but variational autoencoders are an easy modification

Cost function = Input - Output

Read chapter 14 in: https://www.deeplearningbook.org/

## Modelling time evolution of ODEs in chemical networks

Evolving complex chemical networks in compressed latent space



Grassi et al. 2021

## Disentangling Complex Chemistry in Astrochemistry

- Using Conditional Autoencoders to transform data (x) to a lower dimensional representation (z)
- Latent variables (z) should ideally cluster in a physically interpretable way
- Enforcing statistical separation using loss function is an example of active explainability



Figure 2. Distribution of scaled euclidian distances, d, for a sample of chemically identical pairs of stars (blue) and fully randomly sampled pairs of stars (orange). For each model, a scaling is applied to the latents such that the mean distance of chemically identical stars is 1 . Each model includes $T_{\text {eff }}, \log g$ and $[\mathrm{Fe} / \mathrm{H}]$, as the parameters to disentangle from the chemical factors of variation. The top row is evaluated using the noiseless test dataset, the bottom with noise of order SNR=50 added. The first column is evaluated using the FaderDis method, the second using the FactorDis method and the final row using the PolyDis method (after PCA with 50 components),

## Bayesian Neurbl Netuorks



## Recap: The Bayes theorem



Evidence

$$
P(D)=\int P(D \mid \theta) P(\theta) d \theta
$$

# Maximum Likelihood Estimation (MLE) and Maximum A Posteriori (MAP) 

$$
P(\theta \mid D)=\frac{P(D \mid \theta) P(\theta)}{P(D)}
$$

- MLE and MAP are almost the same thing and only differ by the prior distribution

Maximum Likelihood Estimate

$$
\hat{\theta}_{M L E}(D)=\underset{\theta}{\operatorname{argmax}} P(D \mid \theta)
$$

- It's literally the maximum of the likelihood.
- In the case of a Gaussian likelihood, it's equivalent to the lowest $\chi^{2}$



# Maximum Likelihood Estimation (MLE) and Maximum A Posteriori (MAP) 

$$
P(\theta \mid D)=\frac{P(D \mid \theta) P(\theta)}{P(D)}
$$

- It's literally the maximum of the likelihood.
- In the case of a Gaussian likelihood, it's equivalent to the lowest $\chi^{2}$


## Maximum A Posteriori

$$
\begin{aligned}
\hat{\theta}_{M A P}(D) & =\underset{\theta}{\operatorname{argmax}} P(\theta \mid D) \\
& =\underset{\theta}{\operatorname{argmax}} P(D \mid \theta) P(\theta)
\end{aligned}
$$

- It's literally the maximum of the posterior.
- MLE is a special case of MAP



## Going back to our MLP



Two excellent papers: Jospin et al. (2022, arXiv: 2007.06823); Goan \& Fookes (2020, arXiv: 2006.12024)

## Going back to our MLP



$$
\begin{aligned}
& \boldsymbol{y}=\boldsymbol{l}_{n} \\
& \boldsymbol{l}_{i}=s_{i}\left(\boldsymbol{W}_{i} \boldsymbol{l}_{i-1}+\boldsymbol{b}_{i}\right) \\
& \boldsymbol{l}_{0}=\boldsymbol{x},
\end{aligned}
$$

$$
\begin{aligned}
& I=\text { layer } \\
& x=\text { input } \\
& y=\text { output } \\
& W=\text { weights matrix } \\
& b=\text { biases } \\
& s=\text { activation function }
\end{aligned}
$$

Let's collect all model parameters in theta:

$$
\boldsymbol{\theta}=(\boldsymbol{W}, \boldsymbol{b})
$$

## Adding uncertainties to our weights

$$
\begin{array}{ll} 
& \Phi=\text { our approximate model } \\
\boldsymbol{\theta} \sim p(\boldsymbol{\theta}), & \boldsymbol{\theta}=(\boldsymbol{W}, \boldsymbol{b}) \\
\boldsymbol{y}=\Phi_{\boldsymbol{\theta}}(\boldsymbol{x})+\boldsymbol{\epsilon}, & D_{x}=\text { training input data } \\
& D_{y}=\text { training output data }
\end{array}
$$



- By setting the weights to be distributions, we make the model probabilistic
- We can now compute the posterior of the parameters $\theta$ over the training data $D$

$$
p(\boldsymbol{\theta} \mid D)=\frac{p\left(D_{\boldsymbol{y}} \mid D_{\boldsymbol{x}}, \boldsymbol{\theta}\right) p(\boldsymbol{\theta})}{\int_{\boldsymbol{\theta}} p\left(D_{\boldsymbol{y}} \mid D_{\boldsymbol{x}}, \boldsymbol{\theta}^{\prime}\right) p\left(\boldsymbol{\theta}^{\prime}\right) d \boldsymbol{\theta}^{\prime}} \propto p\left(D_{\boldsymbol{y}} \mid D_{\boldsymbol{x}}, \boldsymbol{\theta}\right) p(\boldsymbol{\theta})
$$

## Adding uncertainties to our weights

- Given $p(\theta \mid D)$ we can compute the probability of y given x assuming D :
$p(y \mid x, D)$

$$
p(\boldsymbol{y} \mid \boldsymbol{x}, D)=\int_{\boldsymbol{\theta}} p\left(\boldsymbol{y} \mid \boldsymbol{x}, \boldsymbol{\theta}^{\prime}\right) p\left(\boldsymbol{\theta}^{\prime} \mid D\right) d \boldsymbol{\theta}^{\prime}
$$

The integral $p(y \mid x, \theta)$ is very hard to calculate. It is usually sampled or approximated using Variational Inference (e.g. Normalising Flows)

We will discuss Variational Inference if we have time...

## What's happening in practice



- Replace your standard feed forward layers with probabilistic layers
- The easiest way is to use PyRo or torchnbnn that implements this for you
- We can now compute the posterior of the parameters $\theta$ over the training data
- We don't actually need ALL layers to be probabilistic but only the last layer needs to be

Google Colab notebook:
https://bit.ly/ExoAI_BNN

## Ensemble Bayesian Networks

- Provides an estimate of network uncertainty (epistemic noise)
- Running many networks in an ensemble (average results) will create a stronger predictor

(b) plan-net Ensemble


Plan-net: Cobb et al. (2019)


## Variational Inference

- If $P(\theta \mid D)$ is intractable, don't sample from it, replace it with an approximation

$$
P(\theta \mid D)=\frac{P(D \mid \theta) P(\theta)}{P(D)} \quad P(D)=\int P(D \mid \theta) P(\theta) d \theta
$$

- Instead of sampling an intractable posterior, we can replace it with an approximate distribution $Q(\theta)$
- The idea is to minimise the statistical difference between $Q(x)$ and $P(\theta \mid D)$-> This becomes a fitting, not a sampling problem!
- $Q(x)$ can be any function but often is a multivariate Gaussian



## Reminder: Kullback-Leibler Divergence

-Claude Shannon derived information entropy in 1948
-Derived by Salomon Kullback and Richard Leiber in 1951
-KLD is the most fundamental measure of information theory
-KLD was devised to measure the expected extra information needed if you want to model the right distribution, P , but you assume the wrong distribution Q.
-It measures the 'distance' between two probability distributions

- Note that $D_{K L}(P \| Q) \neq D_{K L}(Q \| P)!!$

$$
D_{K L}(P \| Q)=\int P(y) \log \left(\frac{P(y)}{Q(y)}\right) d y
$$



## Variational Inference

- VI poses the following minimisation:

$$
P(\theta \mid D)=\frac{P(D \mid \theta) P(\theta)}{P(D)}
$$

$$
Q^{*}(\theta)=\underset{Q(\theta) \in \mathscr{Q}}{\operatorname{argmin}} D_{K L}(Q(\theta) \| P(\theta \mid D))
$$

$$
P(D)=\int P(D \mid \theta) P(\theta) d \theta
$$

- VI poses the following minimisation:

$$
P(\theta, D)=P(\theta \mid D) P(\theta)
$$

$$
\begin{aligned}
D_{K L}(Q(\theta) \| P(\theta \mid D)) & =\mathbb{E}_{Q}\left[\log \frac{Q(\theta)}{P(D \mid \theta)}\right] \\
& =\mathbb{E}_{Q}[\log Q(\theta)]-\mathbb{E}_{Q}[\log P(\theta \mid D)] \\
& =\mathbb{E}_{Q}[\log Q(\theta)]-\mathbb{E}_{Q}[\log P(\theta, D)]+P(D) \\
& =-\frac{\left.\mathbb{E}_{Q}[\log P(\theta, D)]-\mathbb{E}_{Q}[\log Q(\theta)]\right)+P(D)}{\mathrm{ELBO}}
\end{aligned}
$$

Hard to compute, Easy to ignore...


## Variational Inference

- If you continue the maths you get

$$
\begin{aligned}
D_{K L}(Q(\theta) \| P(\theta \mid D)) & =\mathbb{E}_{Q}\left[\log \frac{Q(\theta)}{P(D \mid \theta)}\right] \\
= & \underbrace{\left(\mathbb{E}_{Q}[\log P(\theta, D)]-\mathbb{E}_{Q}[\log Q(\theta)]\right)+P(D)}_{\mathrm{ELBO}}
\end{aligned}
$$

$$
\operatorname{ELBO}(Q)=\mathbb{E}[\log P(\theta)]+\mathbb{E}[\log P(D \mid \theta)]-\mathbb{E}[\log Q(\theta)]
$$

$$
=\mathbb{E}[\log P(D \mid \theta)]-D_{K L}(Q(\theta) \| P(\theta))
$$

ur likelihood

Distance of $Q(\theta)$ from Prior $P(\theta)$


[^0]\[

$$
\begin{aligned}
& P(\theta \mid D)=\frac{P(D \mid \theta) P(\theta)}{P(D)} \\
& P(\theta, D)=P(\theta \mid D) P(\theta)
\end{aligned}
$$
\]

## Variational Inference in Variational Autoencoders

- How do we calculate this? Using ML

$$
\begin{aligned}
\operatorname{ELBO}(Q) & =\mathbb{E}[\log P(\theta)]+\mathbb{E}[\log P(D \mid \theta)]-\mathbb{E}[\log Q(\theta)] \\
& =\mathbb{E}[\log P(D \mid \theta)]-D_{K L}(Q(\theta) \| P(\theta))
\end{aligned}
$$

- Variational Autoencoders (VAE) use VI very successfully
- Training the VAE learns an approx. of the posterior $P_{\phi}(\theta \mid D)$ - $\phi$ are the parameters of the VAE

$\theta$ drawn from a
Gaussian distribution

Probabilistic decoder $P_{\phi}(\hat{D} \mid \theta)$

## Normalising flows. Making VI non-Gaussian

- Normalising flows extend the central Gaussian assumption to arbitrary complex distributions
-The do this by repeatedly learning consecutive linear transformations of $\theta$



## Normalising flows. Making VI non-Gaussian

- Normalising flows extend the central Gaussian assumption to arbitrary complex distributions
-The do this by repeatedly learning consecutive linear transformations of $\theta$


Probabilist encoder $P_{\phi}(\theta \mid D)$
Rezende \& Mohamad (2015)

## Normalising flows learning Atmospheric retrievals

- Normalising flows extend the central Gaussian assumption to arbitrary complex distributions
-The do this by repeatedly learning consecutive linear transformations of $\theta$




## Variation Inference vs Sampling results

- Equivalent posteriors to traditional retrievals
- 75\% fewer forward models required
- Full formal treatment of observational errors
- Full ability to do Bayesian model selection

| Model | ELBO | Ref | $\log _{10}(\mathcal{B})$ |
| ---: | :---: | :---: | :---: |
| Flat line | 62.74 | 62.83 | 315.66 |
| No Methane | 345.37 | 347.18 | 33.03 |
| Complete | 378.40 | 380.20 | $\mathrm{~N} / \mathrm{A}$ |
| Overspecified Model | 374.00 | 377.74 | 4.4 |

Yip et al. (2022)

## Variational Inference in Variational Autoencoders

- VAEs are not the only way to do VI but its the most focused on at the moment
- Most distributions used to approximate $P(\theta \mid D)$ are multivariate Gaussians but more complex distributions can be implemented or iteratively learned
- Normalising Flows allow the transformation from Gaussians to arbitrary complex distributions by iteratively applying linear transformations to the Gaussian dists.
- Good blogpost on NFs: https://towardsdatascience.com/introduction-to-normalizing-flows-d002af262a4b



## It's not only about publishing a paper...



## Power vs Explainability



## Concept and Data drift

- Is your model trained on simulations? Are those representative of the data?
- Is your observation/instrument changing?
- Is your data changing in imperceptible ways?
- Is the science question changing?

Original Data


Real concept drift

$p(y \mid X)$ changes

Virtual drift



## Hierarchy of Explainability

## Passive vs Active, Local vs Global Explanations

| Dimension 1 - Passive vs. Active Approaches |  |
| :---: | :---: |
| $\left\{\begin{array}{l}\text { Passive } \\ \text { Active }\end{array}\right.$ | Post hoc explain trained neural networks Actively change the network architecture or training process for better interpretability |
| Dimension 2 - Type of Explanations (in the order of increasing explanatory power) |  |
| To explain a predicti $\begin{aligned} & \text { Examples } \\ & \text { Attribution } \\ & \text { Hidden semantics } \\ & \text { Rules } \end{aligned}$ | n/class by <br> Provide example(s) which may be considered similar or as prototype(s) <br> Assign credit (or blame) to the input features (e.g. feature importance, saliency masks) <br> Make sense of certain hidden neurons/layers <br> Extract logic rules (e.g. decision trees, rule sets and other rule formats) |
| Dimension 3 - Local vs. Global Interpretability (in terms of the input space) |  |
| $\downarrow \begin{aligned} & \text { Local } \\ & \text { Semi-local } \\ & \text { Global }\end{aligned}$ | Explain network's predictions on individual samples (e.g. a saliency mask for an input image) <br> In between, for example, explain a group of similar inputs together <br> Explain the network as a whole (e.g. a set of rules/a decision tree) |



## A number of approaches

- Very fast developing field
- Large number of approaches
- Huge body of literature, see references below for good reviews


## Most recent review papers

- Miller 2019
- Guidotti et al. 2019
- Carvaho et al 2019
- Guo 2020
- Tjoa \& Guan 2020
- Meske et al 2020
- Arietta et al 2020
- Ivanovs et al 2021
- Langer et al 2021
- Sokol \& Flach 2021
- Zhang et al 2021
- See Minh et al 2021 (Artificial Intelligence Review) for a review of review papers
Barredo Arrieta et al. 2020, Information Fusion, 58, 82

Many approaches to XAl!


Barredo Arrieta et al. 2020, Minh et al. 2021


## Localised explainability may sometimes not be enough

The Blind Man and the Elephant parable


Figure from Sokol \& Flach 2021, arXiv: 2112.14466

## But if you have to use AI/ML A quick cheat sheet:

- PCA, clustering and component separation, Random Forests...

Use sklearn (https://scikit-learn.org/stable/index.html)

- Deep learning

Use PyTorch (https://pytorch.org/)

- Probabilistic programming

Use PyRo (https://pyro.ai)

- Simulation based inference

Use SBI (https://www.mackelab.org/sbi/)

- Great resources for models and tutorials

HuggingFace (https://huggingface.co/)
Papers With Code (https://paperswithcode.com/

## Want to try yourself on some Al now?

Have a look at the Ariel Machine Learning Data Challenge


Eetter understand their atmospheres Before they understend aurs!

/imagine prompt: A female scientist analysing an alien in the war of the worlds


Extra slides

## Reparameterisation trick for VAEs

Original form


Deterministic node
Random node

Reparameterised form

[Kingma, 2013]
[Bengio, 2013]
[Kingma and Welling 2014]
[Rezende et al 2014]


[^0]:    Expectation of your likelihood

